

Technology	Pollutants ^a	Description and comment
Absorption	H ₂ S, SO ₂ , HCl, VOCs	A spray scrubber or packed column maintains a high gas-liquid contact area; especially effective for water-soluble species that ca be converted to nonhazardous form in water
Adsorption	VOCs	Contact is promoted between gas and granular sorbent material, such as activated carbon, so that pollutant molecules adhere to surfaces; often the method of choice for controlling nonpolar organics; can be effective when low trace levels of contamination (ppb-ppm) must be achieved; effective in processing large air volumes with dilute contaminants
Incineration	VOCs	Waste gases are burned to convert H to H ₂ O, C to CO ₂ ; commonl applied for low to medium levels of contamination with pure hydrocarbons or oxygenated organics
Catalytic redox	NO, CO, VOCs	Solid catalyst is used to increase rate of reaction and convert elements to less hazardous forms; common application is the three-way catalyst used in motor vehicles
Condensation	VOCs	Phase change from gas to liquid is caused either by cooling or by increasing pressure; requires high gas-phase concentration of species with significant recovery value and high boiling point; cannot achieve very low gas-phase concentrations, so sometimes used as pretreatment technique
Membrane recovery	VOCs	Organic vapors are separated from air by flowing gas past membranes that are more permeable to organics than to air; advanced, newly emerging technology







Techniques to remove particles from an air stream

Table 7.C.1 Control Devices for Capturing Particulate Air Pollutants

Device	Particle size	Collection mechanism and application			
Settling chamber	>~20 µm	Separates particles from a gas stream by gravity; used to treat very dirty air streams that contain very coarse particles			
Cyclone	$>\sim 1 \mu m$	Separates particles by inertia in a vortex flow; common pretreatment process ahead of electrostatic precipitator or fabric filter			
Scrubber	$>\sim 1~\mu m$	Wet collector; induces collisions between particles and water droplets to remove particles from gas stream by inertia; may be used for combined collection of particles and water-soluble gases			
Electrostatic precipitator	All	Creates electrostatic charge on particles so they can be removed by an electric field; high-efficiency device that is used to treat stack gases in industrial processes			
Filter	All	Air flow is forced through matrix of fibers, capturing particles by a combination of Brownian motion, physical straining, interception, and impaction; high efficiency possible; applied for treating waste gases and for removing particles from air before use			

(Nazaroff & Alvarez-Cohen, Table 7.C.1, page 443)









Standard Cyclone Dimensions

Extensive work has been done to determine in what manner dimensions of cyclones affect performance. In some classic work that is still used today, Shepherd and Lapple (1939, 1940) determined "optimal" dimensions for cyclones. Subsequent investigators reported similar work, and the so-called "standard" cyclones were born.

All dimensions are related to the body diameter of the cyclone so that the results can be applied generally.

The table on the next slide summarizes the dimensions of standard cyclones of the three types mentioned in the previous figure. The side figure illustrates the various dimensions used in the table.

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	Cyclone	Туре					D_{e_1}
	High Efficiency		Conventional		High Throughput		. W.
	(1)	(2)	(3)	(4)	(5)	(6)	
Body Diameter, D/D	1.0	1.0	1.0	1.0	1.0	1.0	$\begin{array}{c c} \uparrow\\ H \\ S \\ S \\ \end{array}$
Height of Inlet, H/D	0.5	0.44	0.5	0.5	0.75	0.8	
Width of Inlet, W/D	0.2	0.21	0.25	0.25	0.375	0.35	
Diameter of Gas Exit, D_e/D	0.5	0.4	0.5	0.5	0.75	0.75	
Length of Vortex Finder, S/D	0.5	0.5	0.625	0.6	0.875	0.85	
Length of Body, L_b/D	1.5	1.4	2.0	1.75	1.5	1.7	$\langle \rangle$
Length of Cone, L_c/D	2.5	2.5	2.0	2.0	2.5	2.0	
Diameter of Dust Outlet, D_d/D	0.375	0.4	0.25	0.4	0.375	0.4	D_d

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Cyclone Theory

Collection Efficiency

A very simple model can be used to determine the effects of both cyclone design and operation on collection efficiency.

In this model, gas spins through a number N of revolutions in the outer vortex. The value of N can be approximated as the sum of revolutions inside the body and inside the cone:

$$N = \frac{1}{H} \left(L_b + \frac{L_c}{2} \right)$$

where

N = number of turns inside the device (no units)

- H = height of inlet duct (m or ft)
- L_b = length of cyclone body (m or ft)
- L_c = length (vertical) of cyclone cone (m or ft).

To be collected, particles must strike the wall within the amount of time that the gas travels in the outer vortex. The *gas residence time* in the outer vortex is

 $\Delta t = \text{path length} / \text{speed} = \pi D N / V_i$

where

 Δt = time spent by gas during spiraling descent (sec)

D = cyclone body diameter (m or ft)

- V_i = gas inlet velocity (m/s or ft/s) = Q/WH
- Q = volumetric inflow (m³/s or ft³/s)
- H = height of inlet (m or ft)
- W = width of inlet (m or ft).

The maximum radial distance traveled by any particle is the width of the inlet duct W. The centrifugal force quickly accelerates the particle to its terminal velocity in the outward (radial) direction, with the opposing drag force equaling the centrifugal force. The terminal velocity that will just allow a particle initially at distance W away from the wall to be collected in time is

 $V_t = W/\Delta t$

where V_t = particle drift velocity in the radial direction (m/s or ft/s).

The particle drift velocity is a function of particle size.

Assuming Stokes regime flow (drag force = $3\pi\mu d_p V_i$) and spherical particles subjected to a centrifugal force mv^2/r , with m = mass of particle in excess of mass of air displaced, $v = V_i$ of inlet flow, and r = D/2, we obtain

$$V_t = \frac{(\rho_p - \rho_a) d_p^2 V_i^2}{9 \,\mu D}$$

where

 V_t = terminal drift transverse velocity (m/s or ft/s)

 d_p = diameter of the particle (m or ft)

 $\dot{\rho_p}$ = density of the particle (kg/m³)

 ρ_a^r = air density (kg/m³)

 μ = air viscosity (kg/m.s).



The preceding equation shows that, in theory, the smallest diameter of particles collected with 100% efficiency is directly related to gas viscosity and inlet duct width, and inversely related to the number of effective turns, inlet gas velocity, and density difference between the particles and the gas.

In practice, collection efficiency does, in fact, depend on these parameters. However, the model has a major flaw: It predicts that *all* particles larger than d_p will be collected with 100% efficiency, which is incorrect. This discrepancy is the result of all our approximations.

Lapple (1951) developed a semi-empirical relationship to calculate a "50% cut diameter" $d_{_{DC}}$, which is the diameter of particles collected with 50% efficiency. The expression is

$$d_{pc} = \left[\frac{9\,\mu W}{2\pi\,N\,V_i\,(\rho_p - \rho_a)}\right]^{1/2}$$

where d_{pc} = diameter of particle collected with 50% efficiency.

Note the similarity between the last two equations. The only difference is a factor 2 in the denominator.







Solutio	n					
$N = \frac{1}{H}$	$\left(L_b + \frac{L_c}{2}\right) =$	6 V	$f_i = \frac{Q}{WH} = \frac{Q}{0}$	$\frac{Q}{0.125 D^2} = 2$	1200 m/min =	= 20 m/s
$d_{pc} = $	$\frac{9}{2\pi}\frac{\mu V}{NV_i(\rho_i)}$	$\frac{W}{(a, -\rho_a)} = \sqrt{\frac{2}{2}}$	$\frac{9}{2\pi} \frac{0.25\mu}{6V_i(\rho_p -$	$\frac{\overline{D}}{(\rho_a)} = 5.79$	$0 \times 10^{-6} \mathrm{m} = 5.7$	79 <i>µ</i> m
	Size range (in µm)	Average size d_p (in μ m)	Collection efficiency η	Mass fraction <i>m/M</i>	Contribution to performance $\eta \times m /M$	
	0-2	1	2.9%	0.01	0.029%	
	2-4	3	21.1%	0.09	1.903%	
	4-6	5	42.7%	0.10	4.268%	
	6 – 10	8	65.6%	0.30	19.678%	
	10 - 18	14	85.4%	0.30	25.613%	
	18 - 30	24	94.5%	0.14	11.953%	
	30 - 50	40	97.9%	0.05	4.897%	
	50 - 100	75	99.4%	0.01	0.994%	
				1.00	70.6%	

